# **SPECIFICATIONS**



#### PERFORMANCE

Supply voltage: Performance: Duration of use: Charging time: Lifting: Maximum speed: Tare weight: TTO:

#### **ENVIRONMENT**

Max ambient temperature: Min. Ambient temperature: Humidity:

#### **FLOOR CONDITIONS**

Floor conditions: Bumpiness maximum: Maximum inclination:

#### PALLET LOAD

Euro pallet:		800x1200mm
Industrial pallet:		1000x1200mm (3 runi
Other pallets after release by the Manufacturer		
Max. Load:		1000kg
Max. Load balancing	front/rear:	<mark>60</mark> /40%
Max. Load distributi	on left/right:	<mark>55/</mark> 45%
Max. Load height:		2.3m

#### MATERIALS

Frame: Forks:

SURFACE TREATMENT Frame:

Forks:

Fasteners: Purchased parts:

#### CONTROLS

**Controls Nipper:** HMI: Language: Navigation: Fleet manager: Visualisation:

24V LiFePO4 24V/2x420W/h 4-5h\* 30min 20-80% 130mm (low 93 - high 223mm) 1m/s in main direction 229kg 15000h

30° C 0°C 95% no condensation

Dry, flat, non-dusty 5mm 3%

ners)

Steel Stainless Steel SS304

White pearl with blank Polyurethane coating Black RAL 9005 structure finish Stainless Steel SS304 Galvanised steel Standard supplier finish

PLC controlled 3,5" touchscreen English Natural feature navigation Bluebotics Web based

### **NAVIGATION**

Scanner:

Scanner type:

Scanning height:

Docking station:

# NIPPER DOCKING STATION

Input power supply: Connector: Output power supply:

#### SAFETY

- Sick S300 2d LIDAR safety scanner (main direction)
- Scanners in forks for backwards driving
- 2 Mechanical bumpers in front of forks
- 2 Mechanical bumpers in back of forks
- Torque limitation driving sideways (90° on main direction)
- Two emergency stops on top of vehicle
- Bluespot warning light for visualisation on floor
- Orange direction indicators
- Flashing orange light for awareness at eyelevel in operation mode
- Red and green LED in forks (front and back) for indication of driving direction
- PLd (performance level d)

## **OPTIONS**

#### **Object scanning**

The 'object scanning' solution consists of three (3) Sick TIM320 scanners. These are installed on the Nipper. Two (2) scanners on each side with a 2D vertical plane next to the vehicle and one (1) scanner on top of the vehicle with an obliquely downward facing field.

The Sick scanners have a field of view of 270°. The blind sides of the scanners at the side are directed upwards.



\*according to the standard cycle for comparability

Consists of two separate chargers (each for every fork) 2x 230V~ 50Hz 3,2A 2x EURO connector 2x 29V-17A

2D Lidar 360° navigation

Pepperl + Fuchs 360° High

Between 2 and 2,5m above

Definition scanning

scanning

floor level

#### **DOCUMENTATION & REGULATION**

Manual:	User manual 1x digital
Language:	Standard English (inside EU depending on country)
Certification:	CE

#### **Regulations:**

2006/42/EC 2014/30/EU NEN-EN-ISO 12100:2010 NEN-EN-ISO 4413:2010 NEN-EN-ISO 13849-1:2016 NEN-EN-ISO 13850:2015 NEN-EN-IEC 60204-1: 2006 NEN-EN 1525:1997 NEN-EN1175-1:1998+A1:2010en Machinery Directive EMC-Directive Safety of machinery - General principles for design - Risk assessment and risk reduction Hydraulic fluid power - General rules and safety requirements for systems and their components Safety of machinery - Safety-related parts of control systems - Part 1: General principles for design Safety of machinery - Emergency stop function - Principles for design Safety of machinery - Electrical equipment of machines - Part 1: General requirements Safety of industrial trucks - Driverless trucks and their systems Safety of industrial machinery trucks - Electrical requirements - Part 1: General requirements for battery powered trucks



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